Bilinear Backlund transformation for the KdV equation with a source

This article has been downloaded from IOPscience. Please scroll down to see the full text article.
1991 J. Phys. A: Math. Gen. 24 L273
(http://iopscience.iop.org/0305-4470/24/6/005)
View the table of contents for this issue, or go to the journal homepage for more

Download details:
IP Address: 129.252.86.83
The article was downloaded on 01/06/2010 at 14:10

Please note that terms and conditions apply.

## LETTER TO THE EDITOR

# Bilinear Bäcklund transformation for the $K d v$ equation with a source 

Yoshimasa Matsuno<br>Department of Physics, Faculty of Liberal Arts, Yamaguchi University, Yamaguchi 753, Japan

Receíved 2 January 1991


#### Abstract

A bilinear Bäcklund transformation for the KdV equation with a source is obtained by using the bilinear transformation method. Superposition formulae for solutions are then constructed which satisfy Bianchi's exchange property and it is shown that they have a simple structure when they are written in the bilinear forms. The inverse scattering transform for the equation is also derived from the Bäcklund transformation.


Recently, a new class of coupled soliton equations in two spatial and one temporal dimensions has been proposed [1]. They describe the interaction of a wavepacket of short waves with a single long wave on the $x-y$ plane. It has also been shown that the proposed system of equations includes as special cases various known physical equations. The equation which we consider in this letter is one of these equations and it is written in the form

$$
\begin{align*}
& u_{t}+6 u u_{x}+u_{x x x}=-\int_{-\infty}^{\infty} \mathrm{d} k \nu\left(|\phi|^{2}\right)_{x}  \tag{1}\\
& \phi_{x x}+\left(u+k^{2}\right) \phi=0 \tag{2}
\end{align*}
$$

where $u=u(x, t)$ and $\phi=\phi(x, t ; k)$ are real and complex functions, respectively, $k$ is a real parameter and $\nu=\nu(k, t)$ is a given real function. The subscripts appended to $u$ and $\phi$ denote partial differentiations. The boundary conditions for $u$ and $\phi$ are specified as

$$
\begin{array}{ll}
u \rightarrow 0 & \text { as }|x| \rightarrow \infty \\
\phi=\phi_{0} \mathrm{e}^{\mathrm{i} k x} & \text { as } x \rightarrow-\infty \tag{4}
\end{array}
$$

where $\phi_{0}=\phi_{0}(k, t)$ is a given function. Since when $\phi=0$, (1) and (2) are reduced to the Korteweg-de Vries ( KdV ) equation, we call them the KdV equation with a source. This system of equations has already been shown to be integrable by means of the inverse scattering method $[2,3]$.

The purpose of the present paper is to derive a Bäcklund transformation (BT) of (1) and (2) and to clarify the structure of the вт. The mathematical tool employed here is the bilinear transformation method [4,5]. In particular, it will be shown that superposition formulae for solutions have a simple structure when they are written in the bilinear forms.

First of all, we bilinearize (1) and (2). Introduce the following dependent variable transformations

$$
\begin{align*}
& u=2(\ln f)_{x x}  \tag{5}\\
& \phi=\phi \quad \mathrm{e}^{i k x} g / f \tag{6}
\end{align*}
$$

where $f=f(x, t)$ and $g=g(x, t ; k)$ are real and complex functions, respectively. Substituting (5) and (6) into (1) and (2) and using the boundary conditions (3) and (4), (1) and (2) are transformed into the following system of bilinear equations for $f$ and $g$ :

$$
\begin{align*}
& D_{x}\left(D_{t}+D_{x}^{3}\right) f \cdot f=-\int_{-\infty}^{\infty} \mathrm{d} k \nu\left|\phi_{0}\right|^{2}\left(|g|^{2}-f^{2}\right)  \tag{7}\\
& \left(D_{x}^{2}+2 \mathrm{i} k D_{x}\right) g \cdot f=0 \tag{8}
\end{align*}
$$

Here, the bilinear operators $D_{1}$ and $D_{x}$ are defined by

$$
\begin{equation*}
D_{t}^{m} D_{x}^{n} g \cdot f=\left.\left(\frac{\partial}{\partial t}-\frac{\partial}{\partial t^{\prime}}\right)^{m}\left(\frac{\partial}{\partial x}-\frac{\partial}{\partial x^{\prime}}\right)^{n} g(t, x) f\left(t^{\prime}, x^{\prime}\right)\right|_{\substack{t^{\prime}=t \\ x^{\prime}=x}} \tag{9}
\end{equation*}
$$

Let other solutions of (7) and (8) be $f^{\prime}$ and $g^{\prime}$. We show that $f^{\prime}$ and $g^{\prime}$ are related to $f$ and $g$ by the following Bäckiund transformation:

$$
\begin{align*}
& \left(D_{1}+D_{x}^{3}+\mu\right) f^{\prime} \cdot f=\frac{\mathrm{i}}{4} \int_{-\infty}^{\infty} \mathrm{d} k \nu\left|\phi_{0}\right|^{2}\left(\frac{g^{\prime *} g}{k-\mathrm{i} \lambda}-\frac{g^{\prime} g^{*}}{k+\mathrm{i} \lambda}\right)  \tag{10}\\
& \left(D_{x}^{2}-2 \lambda D_{x}\right) f^{\prime} \cdot f=0  \tag{11}\\
& D_{x} g \cdot f^{\prime}=-(\lambda+\mathrm{i} k)\left(g^{\prime} f+g f^{\prime}\right)  \tag{12}\\
& D_{x} g^{\prime} \cdot f=(\lambda-\mathrm{i} k)\left(g^{\prime} f+g f^{\prime}\right) . \tag{13}
\end{align*}
$$

Here, $\lambda$ and $\mu$ are real Bäcklund parameters which may be $t$-dependent in general and * denotes complex conjugate. First, we prove (12) and (13). For the purpuse, consider the quantity $P$ defined by

$$
\begin{equation*}
P \equiv g^{\prime} f^{\prime}\left(D_{x}^{2}+2 i k D_{x}\right) g \cdot f-g f\left(D_{x}^{2}+2 i k D_{x}\right) g^{\prime} \cdot f^{\prime} \tag{14}
\end{equation*}
$$

Using the formulae for bilinear operators

$$
\begin{align*}
& a b D_{x} c \cdot d-\left(D_{x} a \cdot b\right) c d=-D_{x} a d \cdot c b  \tag{15}\\
& a b D_{x}^{2} c \cdot d-\left(D_{x}^{2} a \cdot b\right) c d=-D_{x}\left[\left(D_{x} a \cdot d\right) \cdot c b+a d \cdot\left(D_{x} c \cdot b\right)\right] \tag{16}
\end{align*}
$$

$P$ is modified in the form

$$
\begin{equation*}
P=-D_{x}\left[\left(D_{x} g^{\prime} \cdot f+\mathrm{i} k g^{\prime} f\right) \cdot g f^{\prime}+g^{\prime} f \cdot\left(D_{x} g \cdot f^{\prime}+\mathrm{i} k g f^{\prime}\right)\right] \tag{17}
\end{equation*}
$$

Substitution of (12) and (13) into (17) yields $P=0$ due to the formula $D_{x} a \cdot a=0$. This implies that if $f$ and $g$ are a pair of solutions of (8), $f^{\prime}$ and $g^{\prime}$ satisfy the same equation, verifying that (12) and (13) are BTs of (8).

Next, introduce the quantity $Q$ defined below to prove (10) and (11).

$$
\begin{align*}
& Q \equiv f^{\prime 2}\left[D_{x}\left(D t+D_{x}^{3}\right) f \cdot f+\int_{-\infty}^{\infty} \mathrm{d} k \nu\left|\phi_{0}\right|^{2}\left(|g|^{2}-f^{2}\right)\right] \\
&-f^{2}\left[D_{x}\left(D_{t}+D_{x}^{3}\right) f^{\prime} \cdot f^{\prime}+\int_{-\infty}^{\infty} \mathrm{d} k \nu\left|\gamma_{0}\right|^{2}\left(\left|g^{\prime}\right|^{2}-f^{\prime 2}\right)\right] \tag{18}
\end{align*}
$$

If we modify (18) with the aid of (15) and the formulae
$b^{2} D_{t} D_{x} a \cdot a-a^{2} D_{t} D_{x} b \cdot b=2 D_{x}\left(D_{t} a \cdot b\right) \cdot a b$
$b^{2} D_{x}^{4} a \cdot a-a^{2} D_{x}^{4} b \cdot b=2 D_{x}\left(D_{x}^{3} a \cdot b\right) \cdot b a+6 D_{x}\left(D_{x}^{2} a \cdot b\right) \cdot\left(D_{x} b \cdot a\right)$
and then substitute (11), (12) and (13) into the resultant expression, we obtain
$Q=-2 D_{x}\left[\left(D_{t}+D_{x}^{3}\right) f^{\prime} \cdot f-\frac{\mathrm{i}}{4} \int_{-\infty}^{\infty} \mathrm{d} k \nu\left|\phi_{0}\right|^{2}\left(\frac{g^{\prime *} g}{k-\mathrm{i} \lambda}-\frac{g^{\prime} g^{*}}{k+\mathrm{i} \gamma}\right)\right] \cdot f^{\prime} f$.
It now readily follows from (10) and the formula $D_{x} a \cdot a=0$ that $Q$ becomes zero, verifying that $f^{\prime}$ and $g^{\prime}$ satisfy (7) provided that $f$ and $g$ satisfy the same equation. Hence, we have completed the proof of the вт, (10)-(13). It should be remarked here that (13) follows from (8), (11) and (12) if we notice the identity

$$
\begin{equation*}
f^{\prime} D_{x}^{2} g \cdot f-g D_{x}^{2} f^{\prime} \cdot f=-2 f_{x} D_{x} g \cdot f^{\prime}+f\left(D_{x} g \cdot f^{\prime}\right)_{x} \tag{22}
\end{equation*}
$$

We now proceed to derive the superposition formulae in terms of bilinear variables. Let ( $f_{1}, g_{1}$ ) and ( $f_{2}, g_{2}$ ) be pairs of solutions of (7) and (8) generated by application of the BT, (11) and (12) to known solutions ( $f_{0}, g_{0}$ ) with the Bäcklund parameters $\lambda_{1}$ and $\lambda_{2}$, respectively. Similarly, let $\left(f_{12}, g_{12}\right)$ and ( $f_{21}, g_{21}$ ) denote pairs of solutions of (7) and (8) obtained by application of the вт with the parameter $\gamma_{2}$ to ( $f_{1}, g_{1}$ ) and with the parameter $\lambda_{1}$ to ( $f_{2}, g_{2}$ ). The situation is represented schematicaliy in figure 1 as a Bianchi diagram.


Figure 1. A Bianchi diagram.
From (11), (12) and the above definitions, the following system of equations must hold:

$$
\begin{align*}
& \left(D_{x}^{2}-2 \lambda_{1} D_{x}\right) f_{1} \cdot f_{0}=0  \tag{23}\\
& \left(D_{x}^{2}-2 \lambda_{2} D_{x}\right) f_{2} \cdot f_{0}=0  \tag{24}\\
& \left(D_{x}^{2}-2 \lambda_{1} D_{x}\right) f_{21} \cdot f_{2}=0  \tag{25}\\
& \left(D_{x}^{2}-2 \lambda_{2} D_{x}\right) f_{12} \cdot f_{1}=0  \tag{26}\\
& D_{x} g_{0} \cdot f_{1}=-\left(\lambda_{1}+\mathrm{i} k\right)\left(g_{1} f_{0}+g_{0} f_{1}\right)  \tag{27}\\
& D_{x} g_{0} \cdot f_{2}=-\left(\lambda_{2}+i k\right)\left(g_{2} f_{0}+g_{0} f_{2}\right)  \tag{28}\\
& D_{x} g_{2} \cdot f_{21}=-\left(\lambda_{1}+\mathrm{i} k\right)\left(g_{21} f_{2}+g_{2} f_{21}\right)  \tag{29}\\
& D_{x} g_{1} \cdot{ }_{12}=-\left(\lambda_{2}+\mathrm{i} k\right)\left(g_{12} f_{1}+g_{1} f_{12}\right) . \tag{30}
\end{align*}
$$

We show that there exist solutions satisfying Bianchi's exchange property, namely $f_{21}=f_{12}$ and $g_{21}=g_{12}$. To do this, we first assume $f_{21}=f_{12}$. It then follows from $(23) \times f_{2} f_{12}-(25) \times f_{0} f_{1}$ and the formula

$$
\begin{equation*}
\left(D_{x}^{2} a \cdot b\right) c d-a b D_{x}^{2} c \cdot d=D_{x}\left[\left(D_{x} a \cdot d\right) \cdot c b+a d \cdot\left(D_{x} c \cdot b\right)\right] \tag{31}
\end{equation*}
$$

that

$$
\begin{equation*}
D_{x}\left[\left(D_{x} f_{1} \cdot f_{2}\right) \cdot f_{0} f_{12}+f_{1} f_{2} \cdot\left(D_{x} f_{12} \cdot f_{0}\right)\right]-2 \lambda_{1} D_{x} f_{1} f_{2} \cdot f_{0} f_{12}=0 \tag{32}
\end{equation*}
$$

By the same way, we have from (24) $\times f_{1} f_{12}-(26) \times f_{0} f_{2}$

$$
\begin{equation*}
D_{x}\left[\left(D_{x} f_{2} \cdot f_{1}\right) \cdot f_{0} f_{12}+f_{1} f_{2} \cdot\left(D_{x} f_{12} \cdot f_{0}\right)\right]-2 \lambda_{2} D_{x} f_{1} f_{2} \cdot f_{0} f_{12}=0 \tag{33}
\end{equation*}
$$

Subtracting (33) from (32) gives

$$
\begin{equation*}
D_{x}\left[D_{x} f_{1} \cdot f_{2}-\left(\lambda_{1}-\lambda_{2}\right) f_{1} f_{2}\right] \cdot f_{0} f_{12}=0 \tag{34}
\end{equation*}
$$

which means that

$$
\begin{equation*}
f_{0} f_{12}=c_{1}\left[D_{x} f_{1} \cdot f_{2}-\left(\lambda_{1}-\lambda_{2}\right) f_{1} f_{2}\right] \tag{35}
\end{equation*}
$$

where $c_{1}$ is an arbitrary constant. Inversely, if we define $f_{12}$ and $f_{21}$ by (35), they satisfy (25) and (26) automatically. The relation (35) represents a superposition formula among four solutions $f_{0}, f_{1}, f_{2}$ and $f_{12}$. One also notes that another superposition formula is derived by adding (32) and (33) as

$$
\begin{equation*}
f_{1} f_{2}=c_{2}\left[D_{x} f_{12} \cdot f_{0}-\left(\lambda_{1}+\lambda_{2}\right) f_{0} f_{12}\right] \tag{36}
\end{equation*}
$$

with $c_{2}$ being an arbitrary constant.
At this stage, we can prove $g_{21}=g_{12}$ under the conditions (35) and $f_{21}=f_{12}$. Indeed, it follows from (29) $\times f_{0}^{2} f_{1}-(30) \times f_{0}^{2} f_{2}$
$R=f_{0}^{2} f_{1} f_{2}\left(g_{12}-g_{21}\right)=\left(g_{2} f_{1}-g_{1} f_{2}\right) f_{0}^{2} f_{12}+\left(\frac{f_{1} D_{x} g_{2} \cdot f_{12}}{\lambda_{1}+\mathrm{i} k}-\frac{f_{2} D_{x} g_{1} \cdot f_{12}}{\lambda_{2}+\mathrm{i} k}\right) f_{0}^{2}$.
Substituting $g_{1}$ and $g_{2}$ obtained from (27) and (28) into (37) and using the formulae

$$
\begin{align*}
& \left(D_{x} a \cdot b\right) c=D_{x} a \cdot b c+a b c_{x}  \tag{38}\\
& d D_{x}\left[a \cdot\left(D_{x} b \cdot c\right)\right]-c D_{x}\left[a \cdot\left(D_{x} b \cdot d\right)\right]=b D_{x}\left[a \cdot\left(D_{x} d \cdot c\right)\right] \tag{39}
\end{align*}
$$

we are led, after some calculations, to the expression

$$
\begin{equation*}
R=\frac{g_{0}}{\left(\lambda_{1}+\mathrm{i} k\right)\left(\lambda_{2}+\mathrm{i} k\right)} D_{x} f_{0} f_{12} \cdot\left[D_{x} f_{1} \cdot f_{2}-\left(\lambda_{1}-\lambda_{2}\right) f_{1} f_{2}\right] . \tag{40}
\end{equation*}
$$

However, due to (35) and $D_{x} a \cdot a=0, R$ vanishes identically. Since $f_{0}^{2} f_{1} f_{2} \neq 0$, we arrive at the required relation $g_{21}=g_{12}$. Thus, we have completed the construction of a commutative Bianchi diagram. If we use (11), (12) and (35), we can generate an infinite sequence of solutions $f_{1}, f_{2}, f_{12}, \ldots, g_{1}, g_{2}, g_{12}, \ldots$ starting from known solutions $f_{0}$ and $g_{0}$ by means of purely algebraic procedure. The bilinear BTs, (10)-(13), and bilinear superposition formulae (35) and (36) are easily transformed into ordinary forms by using (5), (6) and their primed counterparts. However, the explicit expressions are not written down here.

Finally, we conclude this letter by showing that the inverse scattering transform equations for (1) and (2) can be derived from the вт. For this, we introduce the wavefunctions $\psi=\psi(x, t)$ and $\chi=\chi(x, t ; k)$ through the relations $\psi=f^{\prime} / f$ and $\chi=$ $\phi_{0} \mathrm{e}^{\mathrm{i} k x} g^{\prime} / f$. It then turns out by eliminating $f^{\prime}$ and $g^{\prime}$ from (10)-(13) and using (5) and (6) that

$$
\begin{align*}
& \psi_{r}+\psi_{x x x}+3 u \psi_{x}+\mu \psi=A \psi+B \psi_{x}  \tag{41}\\
& \psi_{x x}-2 \lambda \psi_{x}+u \psi=0  \tag{42}\\
& \chi=-(\lambda+i k)^{-1}\left[\left(\phi_{x}+\lambda \phi\right) \psi-\phi \psi_{x}\right]  \tag{43}\\
& \chi_{x}-\lambda \chi=(\lambda-i k) \phi \psi \tag{44}
\end{align*}
$$

with

$$
\begin{align*}
& A=-\frac{1}{4} \int_{-\infty}^{\infty} \mathrm{d} k \frac{\nu}{k^{2}+\lambda^{2}}\left(\frac{\partial}{\partial x}+2 \lambda\right)|\phi|^{2}  \tag{45}\\
& B=\frac{1}{2} \int_{-\infty}^{\infty} \mathrm{d} k \frac{\nu|\phi|^{2}}{k^{2}+\lambda^{2}} . \tag{46}
\end{align*}
$$

One can confirm by direct calculation that the compatibility conditions of (41)-(44) yield (1) and (2).

The author thanks Professor M Nishioka for continual encouragement.

## References

[1] Matsuno Y 1990 J. Phys. A: Math. Gen. 23 L. 1235
[2] Mel'nikov V K 1990 Inverse Problems 6233
[3] Leon J and Latifi A 1990 J. Phys. A: Math. Gen. 231385
[4] Hirota R 1974 Prog. Theor. Phys. 521498
[5] Matsuno Y 1984 Bilinear Transformation Method (New York: Academic)

